

# Flexible Modeling of Transition Processes via Bayesian Spline Rate Models

with Application to Estimating and Projecting Modern Contraceptive Prevalence

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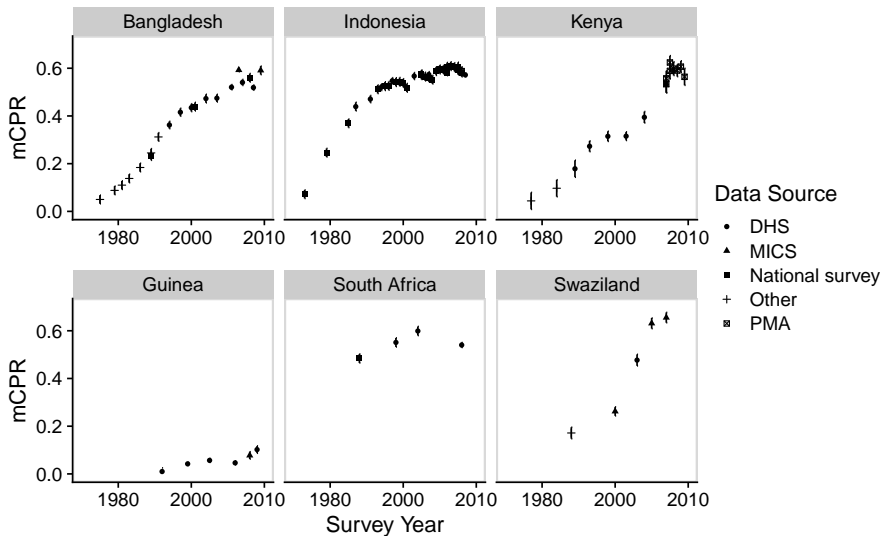
July 2022

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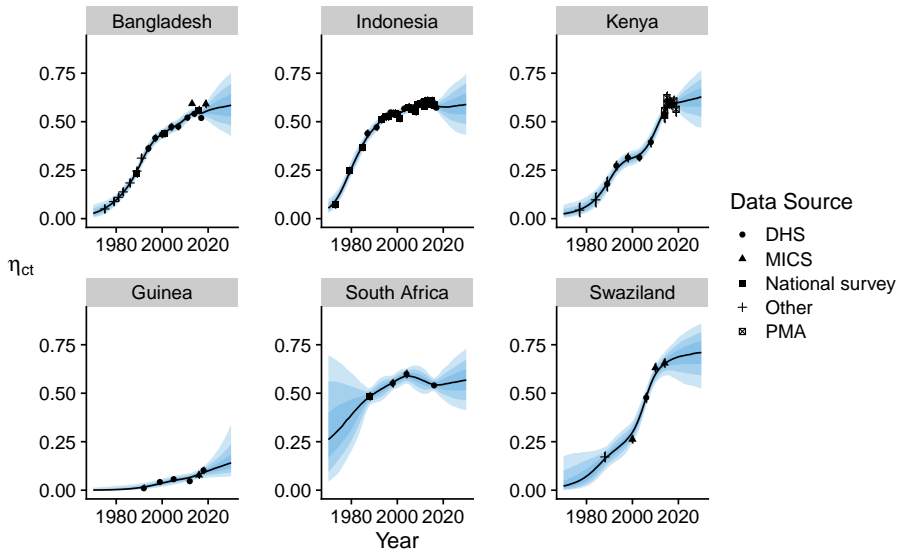
- Increasing interest in estimates and projections of demographic and health indicators.
- Some indicators have been observed to evolve similarly across populations.
  - They tend to follow a *transition* between stable states.
- Classic example: demographic transition.
  - Transition from **high** total fertility rate and **high** under-5 mortality to **low** fertility, **low** mortality.
- Existing statistical models for estimating and projecting trends in these indicators draw on these patterns.
- **This presentation:** We propose a new type of model, called *B-spline Transition Models*, for flexibly estimating indicators that follow transitions.

- **Modern Contraceptive Prevalence Rate (mCPR)** for married or in-union women: proportion of married or in-union women of reproductive age using (or with partner using) a modern contraceptive method.
- Transition: low to high mCPR.
- Existing model: Family Planning Estimation Model (FPEM, Cahill et al. 2018).
- Goal: estimate and project mCPR in countries from 1970-2030.
- Dataset aggregated by United Nations Population Division (UNPD) from surveys conducted by governments or international organizations.

# Raw Data

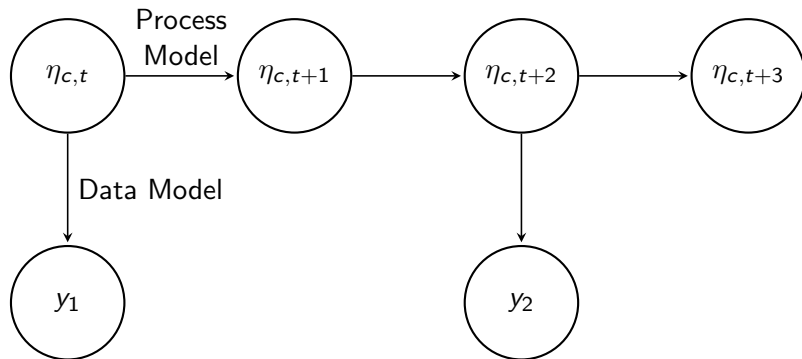


# Example Fits



- Let  $\eta_{c,t}$  be the true value of the indicator in country  $c$  at time  $t$  ( $c = 1, \dots, C, t = 1, \dots, T$ ).
- Observed data  $y_i, i = 1, \dots, n$  with associated properties  $c[i], t[i], \dots$
- *Process model* describes evolution of  $\eta_{c,t}$ .
- *Data model* describes relationship between  $y_i$  and  $\eta_{c[i],t[i]}$ .

# Modeling Framework



# Transition Models

- **Our contribution:** a model class for indicators that follow a transition.
- *Transition Models* have a process model given by

$$g_1(\eta_{c,t}) = \underbrace{g_3(t, \eta_{c,s \neq t}, \alpha_c)}_{\text{systematic}} + \underbrace{\epsilon_{c,t}}_{\text{smoothing}}.$$

- The systematic component has the following form:

$$g_3(t, \eta_{c,s \neq t}, \alpha_c) = \begin{cases} \Omega_c, & t = t_c^*, \\ g_1(\eta_{c,t-1}) + f(\eta_{c,t-1}, P_c, \beta_c), & t > t_c^*, \\ g_1(\eta_{c,t+1}) - f(\eta_{c,t+1}, P_c, \beta_c), & t < t_c^*, \end{cases}$$

where  $\alpha_c = \{\Omega_c, P_c, \beta_c\}$ .

- The function  $f$  is called the *transition function*.



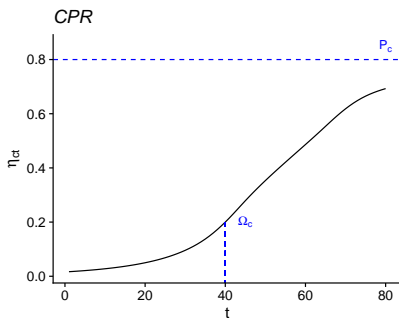
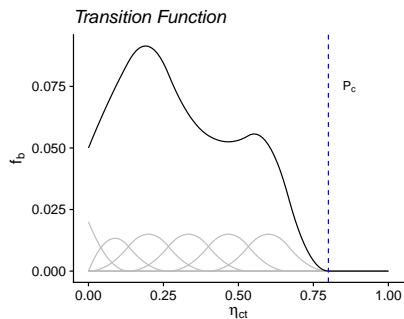
- Define a transition function  $f_b$  as:

$$f_b(\eta_{c,t}, P_c, \beta_c) = \sum_{j=1}^J \underbrace{h_j(\beta_{c,j})}_{\text{coefficient}} \cdot \underbrace{B_j(\eta_{c,t}/P_c)}_{\text{basis function}},$$

where  $P_c$  is an asymptote parameter.

- Flexibility of  $f_b$  can be tuned through the spline degree and number and positioning of knots.

# Example B-spline Transition Function



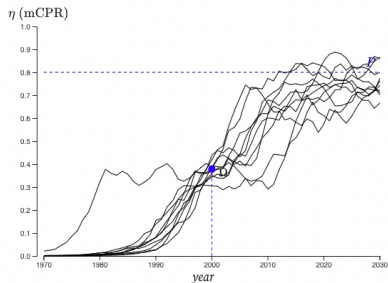
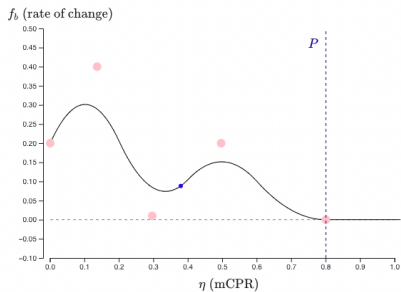
- Recall the process model has two components:

$$g_1(\eta_{c,t}) = \underbrace{g_3(t, \eta_{c,s \neq t}, \alpha_c)}_{\text{systematic}} + \underbrace{\epsilon_{c,t}}_{\text{smoothing}} .$$

- Smoothing component: AR(1) process of the form

$$\epsilon_{c,t} | \epsilon_{c,t-1}, \tau, \rho \sim N(\rho * \epsilon_{c,t-1}, \tau^2)$$

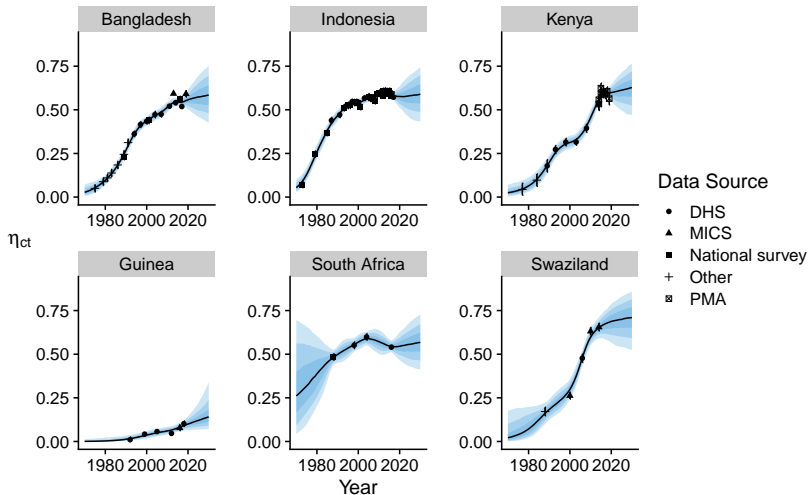
# Smoothing component



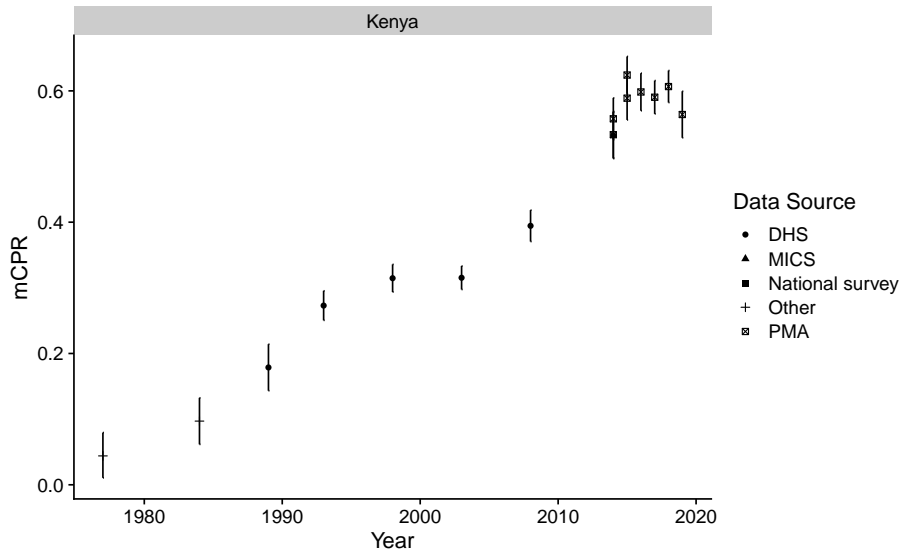
- Let  $y_i$ ,  $i = 1, \dots, n$  be the observed mCPR for country  $c[i]$  and year  $y[i]$  from data source  $d[i]$ .
- For each observation we have an estimate  $s_i^2$  of the sampling error.
- We also expect each data source to have additional non-sampling error  $\sigma_{d[i]}^2$ .
- Truncated normal data model:

$$y_i | \eta_{c[i], t[i]}, \sigma_{d[i]}^2 \sim N_{(0,1)} \left( \eta_{c[i], t[i]}, s_i^2 + \sigma_{d[i]}^2 \right).$$

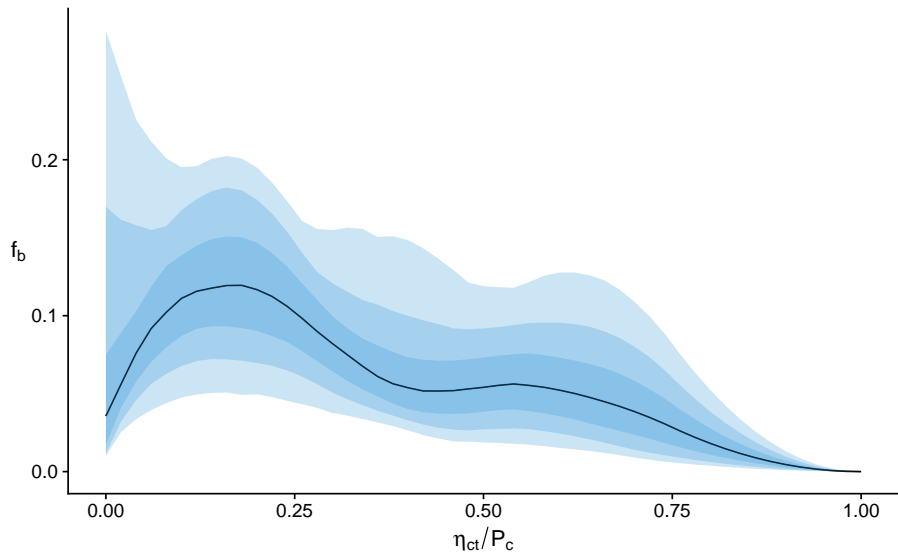
# Illustrative Fits



# Kenya Raw Data

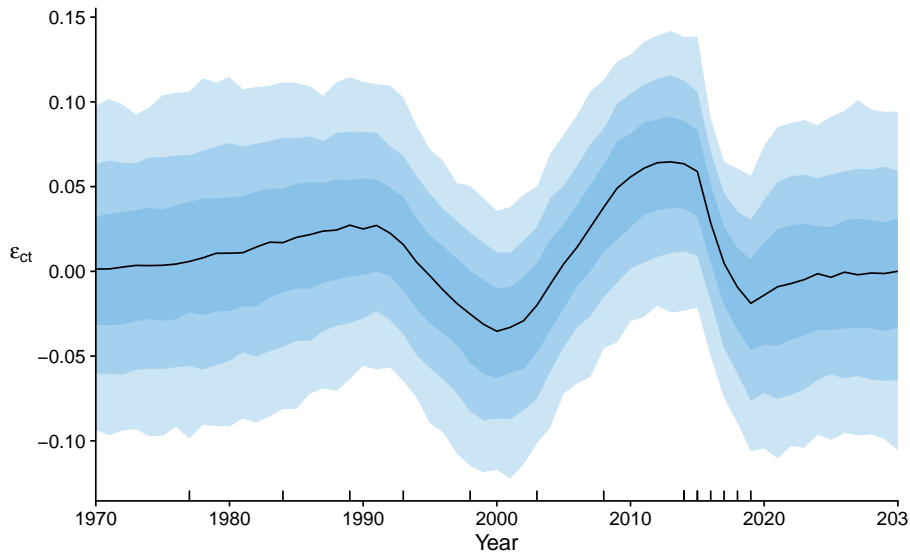


# Kenya Transition Function

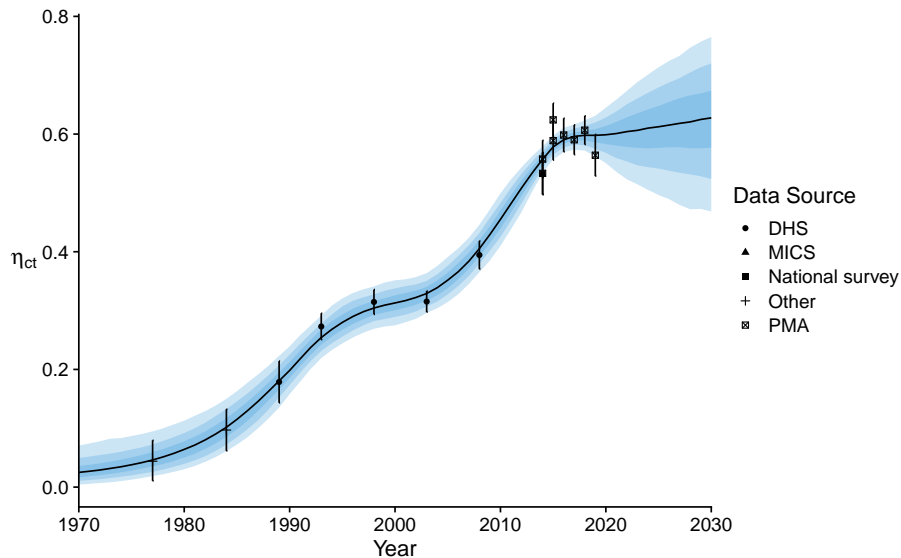




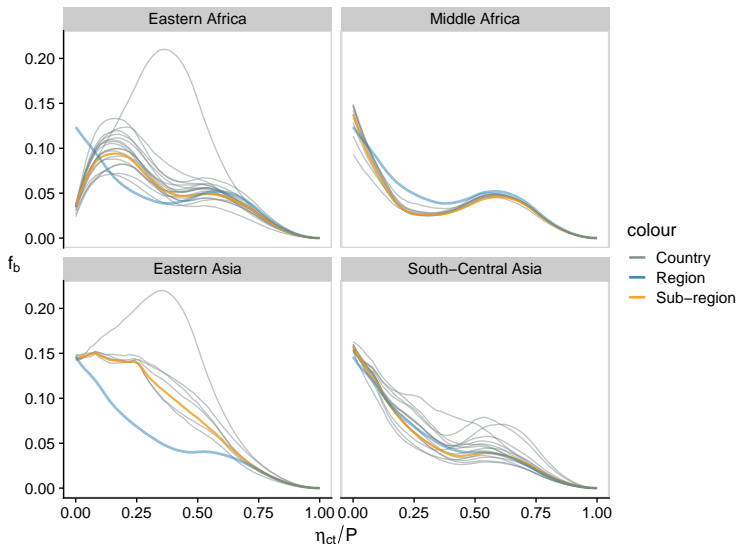
# Kenya Smoothing Component



# Kenya mCPR Estimates



# Trends can be seen in regional and subregional transition functions



- Subclass of *Transition Models* for indicators that follow transitions.
- B-spline Transition Model: flexible modelling approach based on B-splines.
- Generated estimations and projections of mCPR in countries from 1970-2030.
- Found systematically different transitions in countries across regions.
- Flexible model framework that can be easily extended to new settings and use cases.

# Choosing a spline specification

Validation exercise: hold out all observations after a cutoff year  $L = 2010$ .

|   | 95% UI  |            |         |                       | Error           |                  |
|---|---------|------------|---------|-----------------------|-----------------|------------------|
|   | % Below | % Included | % Above | CI Width $\times 100$ | ME $\times 100$ | MAE $\times 100$ |
| Model Check 2 ( $L = 2010$ ), $n = 133$ |         |            |         |                       |                 |                  |
| B-spline ( $d = 2, K = 5$ )             | 3.76%   | 94.7%      | 1.5%    | 32.0                  | -1.670          | 4.64             |
| B-spline ( $d = 2, K = 7$ )             | 6.02%   | 91.7%      | 2.26%   | 31.5                  | -1.260          | 4.68             |
| B-spline ( $d = 3, K = 5$ )             | 3.76%   | 94.7%      | 1.5%    | 32.4                  | -1.630          | 4.48             |
| B-spline ( $d = 3, K = 7$ )             | 3.76%   | 94%        | 2.26%   | 31.6                  | -0.965          | 4.57             |

95% UI: 95% uncertainty interval. ME: median error. MAE: median absolute error.  
Measures calculated using the last held-out observation within each area.

# Sharing information on shape of transition function

